

CV	Name	Description	Range	Default																				
1	Loco address	Short (2 digit) address of locomotive	1 - 127	3																				
2	Start voltage	Minimum speed of the locomotive	1 - 255	3																				
3	Acceleration	This value multiplied by 0.896 is the time from stop to maximum speed	0 - 255	80																				
4	Deceleration	This value multiplied by 0.896 is the time from maximum speed to stop	0 - 255	80																				
5	Maximum speed	Maximum speed of the locomotive	0 - 255	255																				
6	Medium speed	Medium speed of locomotive	0 - 255	88																				
8	Manufacturer's ID	Manufacturers's ID ESU - Writing value 8 in this CV triggers a reset to factory default values	151	-																				
9	Motor PWM frequency	Motor PWM frequency as a multiple of 1000 Hz	10 - 50	40																				
17 & 18	Long address of the loco	Long address of engine (see full manual online at www.loksound.com)																						
19	Consist Address	Additional address for consist operation. Value 0 or 128 means: consist address is disabled 1 – 127 consist address active, normal direction 129 – 255 consist address active reverse direction	0-255	0																				
27	Brake mode	Allowed brake modes		28																				
		<table border="1"> <thead> <tr> <th>Bit</th> <th>Function</th> <th>Value</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>ABC braking, voltage higher on the right hand side</td> <td>1</td> </tr> <tr> <td>1</td> <td>ABC braking, voltage higher on the left hand side</td> <td>2</td> </tr> <tr> <td>2</td> <td>ZIMO® HLU brakes active</td> <td>4</td> </tr> <tr> <td>3</td> <td>Brake on DC, if polarity against driving direction</td> <td>8</td> </tr> <tr> <td>4</td> <td>Brake on DC, if polarity like driving direction</td> <td>16</td> </tr> <tr> <td>7</td> <td>Loco brakes with constant brake distance, if FS=0</td> <td>128</td> </tr> </tbody> </table>	Bit	Function	Value	0	ABC braking, voltage higher on the right hand side	1	1	ABC braking, voltage higher on the left hand side	2	2	ZIMO® HLU brakes active	4	3	Brake on DC, if polarity against driving direction	8	4	Brake on DC, if polarity like driving direction	16	7	Loco brakes with constant brake distance, if FS=0	128	
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28	RailCom® Configuration	Settings for RailCom®		131																				
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29	Configuration register	Calculated field. Add up the values you want to activate, then write this number into CV 29.		12																				
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CV	Name	Description	Range	Default																								
31	Index register H	Should be either "0" or "16" for LokSound Decoders	16	16																								
32	Index register L	CV 32=0 if accessing CVs 1- 255, CV 31=1,2,3 if accessing CVs 257-511	0 - 4	0																								
49	Extended Configuration #1	<table border="1"> <tbody> <tr> <td>0</td> <td>Enable Load control (Back-EMF) Disable Load control (Back-EMF)</td> <td>1 0</td> </tr> <tr> <td>1</td> <td>Reserved</td> <td></td> </tr> <tr> <td>2</td> <td>Reserved</td> <td></td> </tr> <tr> <td>3</td> <td>Märklin® consecutive address „low“-Bit (not for "DCC")</td> <td>0,8</td> </tr> <tr> <td>4</td> <td>Automatic DCC speed step detection Disable DCC speed step detection Enable DCC speed step detection</td> <td>0 16</td> </tr> <tr> <td>5</td> <td>LGB® function button mode Disable LGB® function button mode Enable LGB® function button mode</td> <td>0 32</td> </tr> <tr> <td>6</td> <td>Reserved</td> <td></td> </tr> <tr> <td>7</td> <td>Märklin® consecutive address „High“-Bit (not for "DCC")</td> <td>0,128</td> </tr> </tbody> </table>	0	Enable Load control (Back-EMF) Disable Load control (Back-EMF)	1 0	1	Reserved		2	Reserved		3	Märklin® consecutive address „low“-Bit (not for "DCC")	0,8	4	Automatic DCC speed step detection Disable DCC speed step detection Enable DCC speed step detection	0 16	5	LGB® function button mode Disable LGB® function button mode Enable LGB® function button mode	0 32	6	Reserved		7	Märklin® consecutive address „High“-Bit (not for "DCC")	0,128	0 - 255	19
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50	Analogue mode	Selection of allowed analogue modes	0 - 3	3																								
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51	«K Slow» Cutoff	Internal Speedstep, until «K Slow» is active	0 - 255	10																								
52	BEMF Param. «K Slow»	«K» -Portion of the PI-Controller valid for lower speed steps	0 - 255	10																								
53	Control Reference voltage	Defines the Back EMF voltage, which the motor should generate at maximum speed. The higher the efficiency of the motor, the higher this value may be set. If the engine does not reach maximum speed, reduce this parameter	0 - 255	140																								
54	Load control Parameter «K»	«K»-component of the internal PI-controller. Defines the effect of load control. The higher the value, the stronger the effect of Back EMF control.	0 - 255	50																								
55	Load control Parameter «I»	«I»-component of the internal PI-controller. Defines the momentum (inertia) of the motor. The higher the momentum of the motor (large flywheel or bigger motor), the lower this value has to be set.	0 - 255	100																								
56	BEMF Influence at VMin	0-100%. Defines the "Strength" of the BEMF at minimum speed step	0 - 255	255																								
63	Sound volume «Master»	Master volume for all sounds.	0 - 192	192																								
64	Brake sound threshold «Brake On»	If the actual loco speed step is smaller than or equals the value indicated here, the brake sound is triggered.	0 - 255	100																								
65	Brake sound threshold «Brake Off»	If the actual loco speed step is smaller than the one indicated here (up to 255), the brake sound will be switched off again. .	0 - 255	25																								
66	Forward Trim	Divided by 128 is the factor used to multiply the motor voltage when driving forward. The value 0 deactivates the trim.	0 - 255	128																								
67-94	Speed table	Defines motor voltage for speed steps. The values „in between“ will be interpolated.	0 - 255	-																								

CV	Name	Description	Range	Default																				
95	Reverse Trim	Divided by 128 is the factor used to multiply the motor voltage when driving backwards. Value 0 deactivates the trim.	0 - 255	128																				
113	Power Fail Bypass	The time that the decoder bridges via the PowerPack after an interruption of voltage. Unit: A multiple of 0.016384 sec.	0 - 255	50																				
116	Slow speed BEMF Sampling period	Frequency of BEMF measurement in 0.1 milliseconds at speed step 1	50 - 200	50																				
117	Full speed BEMF Sampling period	Frequency of BEMF measurement in 0.1 milliseconds at speed step 255	50 - 200	150																				
118	Slow speed BEMF Measurement gap length VMin	Length of the BEMF measuring gap in 0.1 milliseconds at speed step 1	10 - 20	150																				
119	Full speed BEMF Measurement gap length Vmax	Length of the BEMF measuring gap in 0.1 milliseconds at speed step 255	10 - 20	15																				
124	Extended Configuration #2	Additional important settings for decoders	-	24																				
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125	Starting voltage Analog DC		0 - 255	30																				
126	Maximum speed Analog DC		0 - 255	130																				
127	Starting voltage AC	(For LokSound 5 Multiprotocol decoders only)	0 - 255	50																				
128	Maximum speed Analog AC	(For LokSound 5 Multiprotocol decoders only)	0 - 255	150																				
134	ABC-Mode „Sensibility“	Threshold, from which asymmetry on ABC shall be recognised.	4 - 32	12																				
155 - 162	Notch Points	Notch Point 1 - Notch Point 8: The internal speed step where the diesel engine sound notches to the next Notch (Not for all sound projects)	0 - 255																					
163	Sound CV9	Horn Select CV	0 - 255	0																				
164	Sound CV10	Bell Select CV	0 - 255	0																				
165	Sound CV11	Brake Squeal Select CV	0 - 255	0																				
166	Sound CV12	Air Dryer Select CV	0 - 255	0																				

Quick Start Guide

LokSound 5 LokSound 5 DCC



LOK SOUND

EST. 1999

Technical Data for LokSound 5 and LokSound 5 DCC Decoders	
Operational modes LokSound 5 DCC	NMRA/DCC with 14, 28, 128 speed steps. 2-digit (short) and 4-digit (long) addresses. Analog DC operation (de-selectable). Automatic recognition of operational mode and DCC speed step selection. DCC Servicemode & DCC POM (Programming on Main). RailCom® Feedback system. RailComPlus® automatic Registration.
Additional Operational modes for LokSound 5	Motorola® with 14, 27, 28 speed steps. Up to 4 addresses (16 Functions) Selectiv® mfxb®-compatible M4 protocol. Automatic registration on all Märklin® command stations Analog AC operation (de-selectable)
Power	Runs all DC and coreless motors. Silent, safe BEMF with up to 50 kHz pulse width frequency Motor output overload protection
Function outputs	8 pin and 21MTC decoders 1.50A continuous load / 2.00 A peak load Next18 / Select Micro and V4.0 decoders 0.75A continuous load / 1.00 A peak load 8 pin decoders 10 outputs (10 powered) 21MTC decoders Up to 14 outputs (10 powered, 4 logic) Next18 / LokSound 5 Micro decoders Up to 9 outputs (6 powered, 3 logic)
Sound	Audio amplifier: 2W @ 4 Ohm load Speaker impedance 4 - 16 Ohms Memory capacity 128 MBit 10 sound channels, each up to 16 Bit 31.250 kHz HiFi Quality Over 280 different sounds!

Warnings

- Do not expose to wet and humid conditions.
- Avoid mechanical force or pressure on the decoder.
- Only use the minimum amount of solder needed.
- Always disconnect power before handling the decoder.
- Never wrap the decoder in electrical tape, as this may cause overheating.
- Make sure that neither the decoder nor any blank wire ends may come into contact with the engine chassis (risk of short circuit).
- Make sure that no wires are squeezed / cut when reassembling the locomotive.
- Never operate a LokSound decoder unattended.

Requirements for Installation

The locomotive must be in perfect operating condition prior to the conversion: Only a locomotive with faultless mechanical properties and smooth running characteristics in analogue mode is worth converting to digital. Check and replace all wear and tear parts such as motor brushes, wheel contacts, light bulbs etc., if necessary.

Installing the Decoder

Locomotives with 8-pin interface

Some LokSound decoders are supplied with an 8-pin plug (refer to Fig 1). Remove the dummy plug from the socket. Insert the plug of the decoder in such a way that pin 1 of the plug (this is the side with the red / orange wires) sits next to the corner of the socket that is usually marked with *, +, • or "1".

Do not rely on the assumption that the wires of the harness have to face in a certain direction: the only reliable reference is the marking of pin 1.

Pin	Description	Color
1	Right motor terminal	orange
2	Rear light	yellow
3	Output AUX1	green
4	Left track terminal	black
5	Left motor terminal	gray
6	Head light	white
7	Common (+pole)	blue
8	Right track terminal	red

Fig. 1: LokSound with 8-pin interface

Locomotives with 21MTC interface

Some LokSound decoders are supplied with a 21MTC interface (fig. 2) You can insert the decoder in two ways: either the pins are put through the decoder (most common); the socket of the decoder remains visible after installation (mounting on top) or the decoder is inserted in such a way that the pins go straight into the socket. Which of the two mounting positions is the correct one depends solely on the locomotive. The position of the marker-pin is the crucial indicator. Plug the decoder into the socket in such a way that the locomotive interface corresponds with the decoder. Do not apply too much pressure when inserting the plug. The decoder must go in without force.

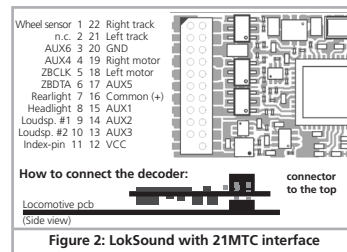


Figure 2: LokSound with 21MTC interface

Locomotives without interface

All LokSound decoders have an interface (plug). There is no "wires-only" version. Please remove the plug at the end of the harness should hard wiring become necessary.

First, please cut all wires installed in the locomotive. Take special care to remove any connections to the chassis (ground): the motor leads must be positively potential-free, in other words they may not have any contact to the chassis or body or the wheels and wheel contacts. Figure 3 and Figure 4 shows all connections.

Function outputs

You can wire all kind of loads to the function outputs.

⚠ Please make sure that the load does not exceed the permitted maximum current and there are no short circuits. The outputs of the LokSound have protection but if an external voltage is applied, the outputs may suffer damage or destruction.

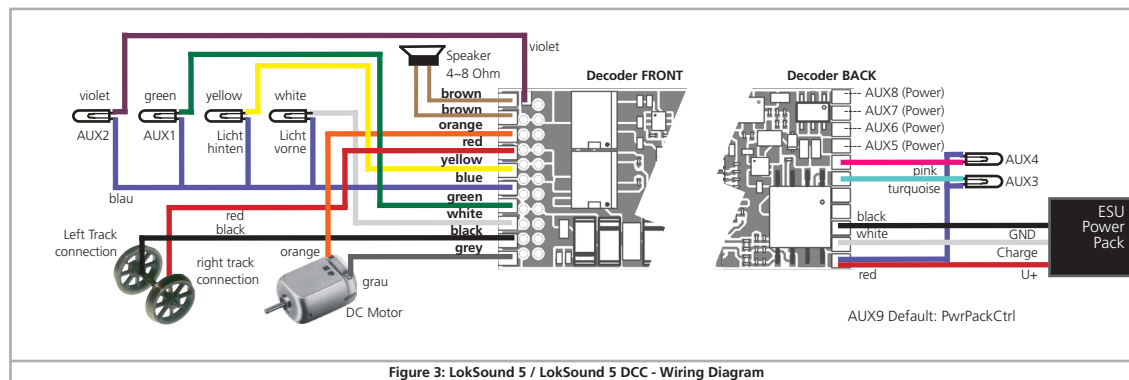


Figure 3: LokSound 5 / LokSound 5 DCC - Wiring Diagram

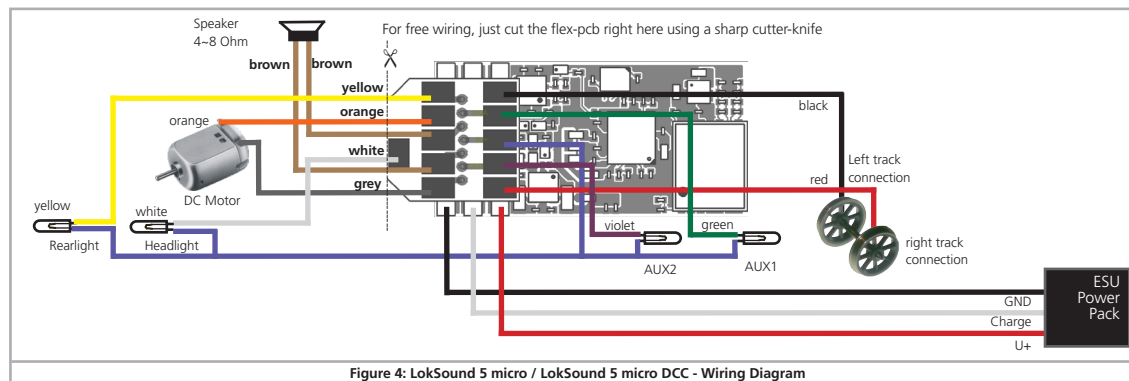


Figure 4: LokSound 5 micro / LokSound 5 micro DCC - Wiring Diagram

For the Large Scale LokSound 5 L and LokSound 5 XL decoders please refer to the Full ESU LokSound 5 User Manual for hook up instructions.

See the full manual online at www.loksound.com

Only install bulbs rated 16V or higher and with a nominal current draw, that does not exceed 50 mA. If you like to use LEDs, a resistor with a rating between 470 Ohms and 2.2 kOhms need to be wired in series. Running the LED without resistor will lead to their immediate destruction!

DCC Operation

i The LokSound works with any DCC system. Remove any capacitors that are wired into the track feeders. This could impair the functionality of the decoder.

The address is set to 03 with 28 speed steps.

Decoder Reset

You can reset the decoder to the default settings at any time. In most cases POM programming will not work to reset a decoder. Please use a separate programming track.

Enter the value 08 into CV 08.

⚠ To complete the reset, power to the decoder must be interrupted.

Volume Control

Master volume is controlled with CV 63. The range is 0 - 192. Individual volumes (CVs as shown) range from 0 - 128

BEMF Autotune Function

Set CV54 to a value of 0, place loco on Mainline and press F1 on your throttle. Loco will quickly take off then stop. Please leave about 5 feet in front of the loco for movement. Once loco stops BEMF is Auto tuned and you continue to operate as normal. You may adjust the BEMF values found by the Auto Tune function manually after autotune.

Default Function Assignment - DIESEL		
Function	Effect	Volume CV
F0	Directional Headlights	-
F1	Bell	283
F2	Playable Airhorn	275
F3	Coupler	291
F4	Dynamic Brake	299
F5	AUX3 (Rotary Beacon)	-
F6	AUX1 + AUX2 (Front) Ditchlights	-
F7	Flange Squeal	435
F8	Sound (On / Off)	259,451,459
F9	Drive Hold	-
F10	Locomotive (Independent) Brake	339
F11	Radiator (Fan) Sound	315
F12	Dimmer (Headlights)	-
F13	AUX4 AUX 5(Rear Ditchlights)	-
F14	Handbrake	363
F15	Isolation Switch	419
F16	Air Dryers on Shutdown	-
F17	Auto Brake Set / Brake Release	483
F18	Sanding Valve	355
F19	Short Air Let Off	443
F20	Compressor	307
F21	Air Dryler	387
F22	Cab Door	371
F23	Engine Compartment doors	379
F24	Reverser Center (Shift 5)	411
F25	Shutters Open/Closed	507
F26	Manual Notching Up	-
F27	Manual Notching Down	-
F28	Manual Notching Logic	-
F29	Automatic Brake Emergency	323
F30	Automatic Brake	331
F31	Soundfader	-

⚠ Make sure that Index CV 31 is set to 16 and Index CV 32 is set to 1 before changing a volume CV

i All function buttons are fully mappable. This allows you to customize your Function Assignments in any way you wish. Please see our full manual for information on how to arrange this.